

Example of Curvilinear Coordinates

We consider the case of polar coordinates. The coordinate functions are

$$\begin{aligned}\xi_1 &= (x^2 + y^2)^{(1/2)} \equiv r \\ \xi_2 &= \text{atan}(y/x) \equiv \theta \\ \xi_3 &= z\end{aligned}$$

So that

$$\frac{\partial}{\partial x_i} \xi_j = \begin{pmatrix} x/r & y/r & 0 \\ -y/r^2 & x/r^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

and the scale factors are the inverses of the lengths of each of the row vectors:

$$\begin{aligned}h_1 &= 1 \\ h_2 &= r \\ h_3 &= 1\end{aligned}$$

The transformation matrix is given by

$$\begin{aligned}\gamma_{ij} &= h_i \frac{\partial}{\partial x_j} \xi_i = \begin{pmatrix} x/r & y/r & 0 \\ -y/r & x/r & 0 \\ 0 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}\end{aligned}$$

From these relationships, we find the gradient

$$(\text{grad } \phi) = \frac{1}{h_i} \frac{\partial}{\partial \xi_i} \phi = \begin{pmatrix} \frac{\partial}{\partial r} \phi \\ \frac{1}{r} \frac{\partial}{\partial \theta} \phi \\ \frac{\partial}{\partial z} \phi \end{pmatrix}$$

The divergence can be written as

$$\begin{aligned}\text{div } \mathbf{F} &= \gamma_{ji} \frac{1}{h_j} \frac{\partial}{\partial \xi_j} \gamma_{mi} F'_m \\ &= \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} F'_r \\ F'_\theta \\ F'_z \end{pmatrix} \\ &= \frac{1}{r} \frac{\partial}{\partial r} (r F'_r) + \frac{1}{r} \frac{\partial}{\partial \theta} F'_\theta + \frac{\partial}{\partial z} F'_z\end{aligned}$$

You can also obtain this from the formula

$$\begin{aligned} \text{div } \mathbf{F} &= \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial \xi_j} \left(\frac{h_1 h_2 h_3}{h_j} F'_j \right) = \frac{1}{r} \frac{\partial}{\partial \xi_j} \left(\frac{r}{h_j} F'_j \right) \\ &= \frac{1}{r} \frac{\partial}{\partial r} (r F'_r) + \frac{1}{r} \frac{\partial}{\partial \theta} F'_\theta + \frac{1}{r} \frac{\partial}{\partial z} (r F'_z) \end{aligned}$$

The curl can be found from

$$\begin{aligned} \text{curl } \mathbf{F} &= \gamma_{il} \epsilon_{ljk} \gamma_{mj} \frac{1}{h_m} \frac{\partial}{\partial \xi_m} \gamma_{nk} F'_n = \\ &= \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \left[\begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial z} \end{pmatrix} \times \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} F'_r \\ F'_\theta \\ F'_z \end{pmatrix} \right] \\ &= \begin{pmatrix} \frac{1}{r} \frac{\partial}{\partial \theta} F'_z - \frac{\partial}{\partial z} F'_\theta \\ \frac{\partial}{\partial z} F'_r - \frac{\partial}{\partial r} F'_z \\ \frac{\partial}{\partial r} F'_\theta + \frac{1}{r} F'_\theta - \frac{1}{r} \frac{\partial}{\partial \theta} F'_r \end{pmatrix} \end{aligned}$$

Again this can be obtained from the formula

$$\text{curl } \mathbf{F} = \epsilon_{ijk} \frac{1}{h_j h_k} \frac{\partial}{\partial \xi_j} (h_k F'_k) = \epsilon_{ijk} \frac{h_i}{h_1 h_2 h_3} \frac{\partial}{\partial \xi_j} (h_k F'_k)$$

The transformed accelerations look like

$$\begin{aligned} \mathbf{A} &= \frac{\partial}{\partial t} u'_i + \gamma_{ik} \gamma_{mj} u'_m \gamma_{nj} \frac{1}{h_n} \frac{\partial}{\partial \xi_n} \gamma_{sk} u'_s \\ &= \frac{\partial}{\partial t} u'_i + \gamma_{ik} u'_j \frac{1}{h_j} \frac{\partial}{\partial \xi_j} \gamma_{sk} u'_s \\ &= \begin{pmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \left(u' \frac{\partial}{\partial r} + \frac{v'}{r} \frac{\partial}{\partial \theta} + w' \frac{\partial}{\partial z} \right) \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} u' \\ v' \\ w' \end{pmatrix} \end{aligned}$$

Using a product rule and working through the derivatives gives

$$\mathbf{A} = \frac{\partial}{\partial t} u'_i + \begin{pmatrix} (u' \frac{\partial}{\partial r} + \frac{v'}{r} \frac{\partial}{\partial \theta} + w' \frac{\partial}{\partial z}) u' - \frac{v'^2}{r} \\ (u' \frac{\partial}{\partial r} + \frac{v'}{r} \frac{\partial}{\partial \theta} + w' \frac{\partial}{\partial z}) v' + \frac{u' v'}{r} \\ (u' \frac{\partial}{\partial r} + \frac{v'}{r} \frac{\partial}{\partial \theta} + w' \frac{\partial}{\partial z}) w' \end{pmatrix}$$

If we use the vector form

$$\begin{aligned} \mathbf{A} &= \frac{\partial}{\partial t} \mathbf{u} + \frac{\partial}{\partial t} \mathbf{u} + \text{grad} \left(\frac{\mathbf{u} \cdot \mathbf{u}}{2} \right) - \mathbf{u} \times \text{curl } \mathbf{u} \\ &= \frac{\partial}{\partial t} u'_i + u'_j \frac{1}{h_j} \frac{\partial}{\partial \xi_j} u'_i + \frac{u'_i u'_j}{h_i} \frac{1}{h_j} \frac{\partial}{\partial \xi_j} h_i - \frac{u'_j u'_j}{h_j} \frac{1}{h_i} \frac{\partial}{\partial \xi_i} h_j \\ &= \frac{\partial}{\partial t} u'_i + u'_j \frac{1}{h_j} \frac{\partial}{\partial \xi_j} u'_i + u'_i u'_j \frac{1}{h_j} \frac{\partial}{\partial \xi_j} \log h_i - u'_j u'_j \frac{1}{h_i} \frac{\partial}{\partial \xi_i} \log h_j \end{aligned}$$

we end up at the same point fairly easily.